

Patrician College of Arts and Science

Department of Mathematics

Linear Algebra

TAM6A

Even Semester

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VECTOR SPACES AND SUBSPACES

- **Definition:** A **vector space** is a nonempty set V of objects, called *vectors*, on which are defined two operations, called *addition and multiplication by scalars* (real numbers), subject to the ten axioms (or rules) listed below. The axioms must hold for all vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} in V and for all scalars c and d .
 1. The sum of \mathbf{u} and \mathbf{v} , denoted by $\mathbf{u} + \mathbf{v}$, is in V .
 2. $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$.
 3. $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$.
 4. There is a zero vector $\mathbf{0}$ in V such that $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$.

VECTOR SPACES AND SUBSPACES

5. For each \mathbf{u} in V , there is a vector $-\mathbf{u}$ in V such that $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$.
6. The scalar multiple of \mathbf{u} by c , denoted by $c\mathbf{u}$, is in V .
7. $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$.
8. $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$.
9. $c(d\mathbf{u}) = (cd)\mathbf{u}$.
10. $1\mathbf{u} = \mathbf{u}$.

VECTOR SPACES AND SUBSPACES

- **Example 1.** The space of all 3×3 matrices is a vector space. The space of all matrices is **not** a vector space.

SUBSPACES

- **Definition:** A **subspace** of a vector space V is a subset H of V that has three properties:
 - a. The zero vector of V is in H .
 - b. H is closed under vector addition. That is, for each \mathbf{u} and \mathbf{v} in H , the sum $\mathbf{u} + \mathbf{v}$ is in H .
 - c. H is closed under multiplication by scalars. That is, for each \mathbf{u} in H and each scalar c , the vector $c\mathbf{u}$ is in H .

SUBSPACES

- Properties (a), (b), and (c) guarantee that a subspace H of V is itself a *vector space*, under the vector space operations already defined in V .
- Every subspace is a vector space.
- Conversely, every vector space is a subspace (of itself and possibly of other larger spaces).

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- **Example 1.** The space of all 3×3 upper triangular matrices is a subspace. The space of all matrices with integer entries is not.

A SUBSPACE SPANNED BY A SET

- The set consisting of only the zero vector in a vector space V is a subspace of V , called the **zero subspace** and written as $\{\mathbf{0}\}$.
- As the term **linear combination** refers to any sum of scalar multiples of vectors, and $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ denotes the set of all vectors that can be written as linear combinations of $\mathbf{v}_1, \dots, \mathbf{v}_p$.

A SUBSPACE SPANNED BY A SET

- **Example 2:** Given \mathbf{v}_1 and \mathbf{v}_2 in a vector space V , let $H = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$. Show that H is a subspace of V .
- **Solution:** The zero vector is in H , since $\mathbf{0} = 0\mathbf{v}_1 + 0\mathbf{v}_2$.
- To show that H is closed under vector addition, take two arbitrary vectors in H , say,

$$\mathbf{u} = s_1\mathbf{v}_1 + s_2\mathbf{v}_2 \quad \text{and} \quad \mathbf{w} = t_1\mathbf{v}_1 + t_2\mathbf{v}_2.$$

- By Axioms 2, 3, and 8 for the vector space V ,

$$\begin{aligned}\mathbf{u} + \mathbf{w} &= (s_1\mathbf{v}_1 + s_2\mathbf{v}_2) + (t_1\mathbf{v}_1 + t_2\mathbf{v}_2) \\ &= (s_1 + t_1)\mathbf{v}_1 + (s_2 + t_2)\mathbf{v}_2\end{aligned}$$

A SUBSPACE SPANNED BY A SET

- **Theorem 1:** If $\mathbf{v}_1, \dots, \mathbf{v}_p$ are in a vector space V , then $\text{Span} \{ \mathbf{v}_1, \dots, \mathbf{v}_p \}$ is a subspace of V .
- We call $\text{Span} \{ \mathbf{v}_1, \dots, \mathbf{v}_p \}$ **the subspace spanned** (or **generated**) by $\{ \mathbf{v}_1, \dots, \mathbf{v}_p \}$.
- Give any subspace H of V , a **spanning** (or **generating**) set for H is a set $\{ \mathbf{v}_1, \dots, \mathbf{v}_p \}$ in H such that

$$H = \text{Span} \{ \mathbf{v}_1, \dots, \mathbf{v}_p \}.$$

KERNEL AND RANGE OF A LINEAR TRANSFORMATION

- **Definition:** A linear transformation T from a vector space V into a vector space W is a rule that assigns to each vector \mathbf{x} in V a unique vector $T(\mathbf{x})$ in W , such that
 - $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ for all \mathbf{u}, \mathbf{v} in V , and
 - $T(c\mathbf{u}) = cT(\mathbf{u})$ for all \mathbf{u} in V and all scalars c .

KERNEL AND RANGE OF A LINEAR TRANSFORMATION

- The **kernel** (or **null space**) of such a T is the set of all \mathbf{u} in V such that $T(\mathbf{u}) = \mathbf{0}$ (the zero vector in W).
- The **range** of T is the set of all vectors in W of the form $T(\mathbf{x})$ for some \mathbf{x} in V .
- The kernel of T is a subspace of V .
- The range of T is a subspace of W .



Thank you

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